

## AMC1202 精密、±50mV 输入、基本隔离放大器

### 1 特性

- ±50mV 输入电压范围，针对使用分流电阻器测量电流进行了优化
- 固定增益：41
- 低直流误差：
  - 失调电压误差：±50μV (最大值)
  - 温漂：±0.8μV/°C (最大值)
  - 增益误差：±0.2% (最大值)
  - 增益漂移：±35ppm/°C (最大值)
  - 非线性度：0.03% (最大值)
- 高侧和低侧以 3.3V 或 5V 电压运行
- 失效防护输出
- 高 CMTI：100kV/μs (最小值)
- 低 EMI，符合 CISPR-11 和 CISPR-25 标准
- 安全相关认证：
  - 4250-V<sub>PK</sub> 基本隔离，符合 DIN VDE V 0884-11：2017-01
  - 符合 UL1577 标准且长达 1 分钟的 3000V<sub>RMS</sub> 隔离

### 2 应用

- 基于分流电阻器的电流感应，可用于：
  - HEV/EV 充电桩
  - HEV/EV 车载充电器 (OBC)
  - HEV/EV 直流/直流转换器
  - HEV/EV 牵引逆变器

### 3 说明

AMC1202 是一款隔离式精密放大器，此放大器的输出与输入电路由抗电磁干扰性能极强的隔离层隔开。该隔离栅经认证可提供高达 3kV<sub>RMS</sub> 的基本电隔离，符合 VDE V 0884-11 和 UL1577 标准，并且可支持最高 1 kV<sub>RMS</sub> 的工作电压。

该隔离栅可将系统中以不同共模电压电平运行的各器件隔开，并保护电压较低的器件免受高电压冲击。

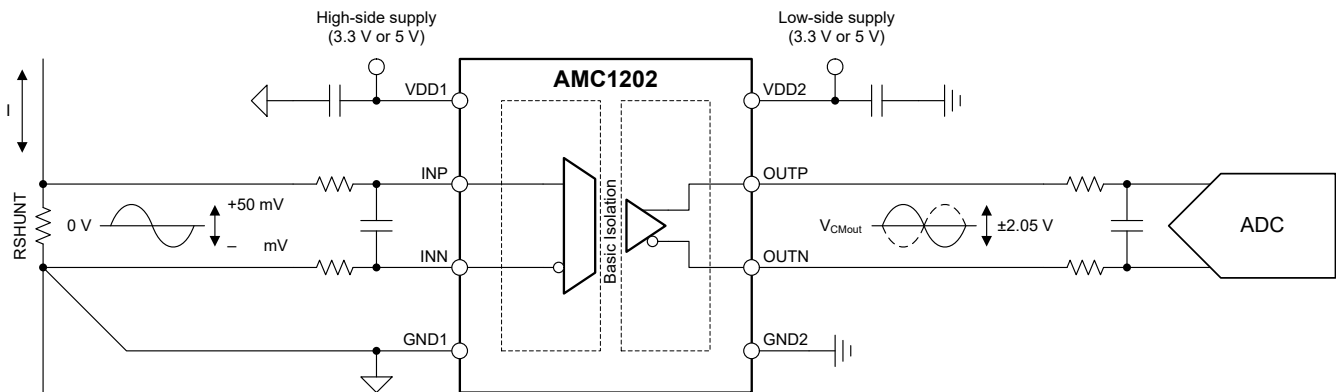
AMC1202 的输入针对直接连接低阻抗分流电阻器或其他具有低信号电位的低阻抗电压源的情况进行了优化。出色的直流精度和低温漂支持在 -40°C 至 +125°C 的整个汽车温度范围内，在 PFC 级、直流/直流转换器、牵引逆变器和 OBC 中进行精确的电流控制。

集成的无分流器和无高侧电源检测功能可简化系统级设计和诊断。

#### 器件信息(1)

| 器件型号    | 封装       | 封装尺寸 (标称值)      |
|---------|----------|-----------------|
| AMC1202 | SOIC (8) | 5.85mm × 7.50mm |

(1) 如需了解所有可用封装，请参阅数据表末尾的可订购产品附录。



典型应用



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## 4 Revision History

注：以前版本的页码可能与当前版本的页码不同

| DATE     | REVISION | NOTES           |
|----------|----------|-----------------|
| May 2021 | *        | Initial Release |

## 5 Pin Configuration and Functions

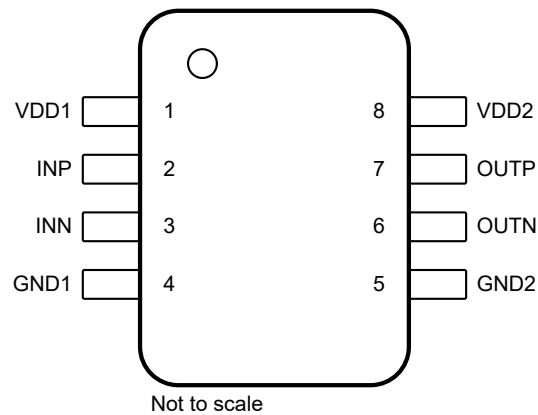


图 5-1. DWV Package, 8-Pin SOIC, Top View

表 5-1. Pin Functions

| PIN |      | TYPE             | DESCRIPTION  |
|-----|------|------------------|--|
| NO. | NAME |                  |  |
| 1   | VDD1 | High-side power  | High-side power supply. <sup>(1)</sup>   |
| 2   | INP  | Analog input     | Noninverting analog input. Either INP or INN must have a DC current path to GND1 to define the common-mode input voltage. <sup>(2)</sup> |
| 3   | INN  | Analog input     | Inverting analog input. Either INP or INN must have a DC current path to GND1 to define the common-mode input voltage. <sup>(2)</sup>    |
| 4   | GND1 | High-side ground | High-side analog ground.   |
| 5   | GND2 | Low-side ground  | Low-side analog ground.  |
| 6   | OUTN | Analog output    | Inverting analog output.   |
| 7   | OUTP | Analog output    | Noninverting analog output.  |
| 8   | VDD2 | Low-side power   | Low-side power supply. <sup>(1)</sup>  |

(1) See the [Power Supply Recommendations](#) section for power-supply decoupling recommendations.

(2) See the [Layout](#) section for details.

## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating ambient temperature range (unless otherwise noted)<sup>(1)</sup>

|                      |  | MIN        | MAX        | UNIT |
|----------------------|--|------------|------------|------|
| Power-supply voltage | High-side VDD1 to GND1                       | -0.3       | 6.5        | V    |
|                      | Low-side VDD2 to GND2                        | -0.3       | 6.5        | V    |
| Analog input voltage | INP, INN                                     | GND1 - 6   | VDD1 + 0.5 | V    |
| Output voltage       | OUTP, OUTN                                   | GND2 - 0.5 | VDD2 + 0.5 | V    |
| Input current        | Continuous, any pin except power-supply pins | -10        | 10         | mA   |
| Temperature          | Junction, T <sub>J</sub>                     |            | 150        | °C   |
|                      | Storage, T <sub>stg</sub>                    | -65        | 150        |      |

- (1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime

### 6.2 ESD Ratings

|                    |                         |   | VALUE | UNIT |
|--------------------|-------------------------|---|-------|------|
| V <sub>(ESD)</sub> | Electrostatic discharge | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup> | ±2000 | V    |
|                    |                         | Charged device model (CDM), per JESD22-C101 <sup>(2)</sup>        | ±1000 |      |

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.  
 (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

over operating ambient temperature range (unless otherwise noted)

|                          |   |   | MIN    | NOM | MAX        | UNIT |
|--------------------------|---|---|--------|-----|------------|------|
| <b>POWER SUPPLY</b>      |   |   |        |     |            |      |
|                          | High-side power supply                            | VDD1 to GND1  | 3      | 5   | 5.5        | V    |
|                          | Low-side power supply                             | VDD2 to GND2  | 3      | 3.3 | 5.5        | V    |
| <b>ANALOG INPUT</b>      |   |   |        |     |            |      |
| V <sub>Clipping</sub>    | Differential input voltage before clipping output | V <sub>IN</sub> = V <sub>INP</sub> - V <sub>INN</sub> |        | ±64 |            | mV   |
| V <sub>FSR</sub>         | Specified linear differential full-scale voltage  | V <sub>IN</sub> = V <sub>INP</sub> - V <sub>INN</sub> | -50    |     | 50         | mV   |
| V <sub>CM</sub>          | Operating common-mode input voltage               | (V <sub>INP</sub> + V <sub>INN</sub> ) / 2 to GND1    | -0.032 |     | VDD1 - 2.2 | V    |
| <b>TEMPERATURE RANGE</b> |   |   |        |     |            |      |
| T <sub>A</sub>           | Specified ambient temperature                     |   | -55    |     | 125        | °C   |

## 6.4 Thermal Information

| THERMAL METRIC <sup>(1)</sup> |  | AMC1202    | UNIT |
|-------------------------------|--|------------|------|
|                               |  | DWV (SOIC) |      |
|                               |  | 8 PINS     |      |
| $R_{\theta JA}$               | Junction-to-ambient thermal resistance       | 85.4       | °C/W |
| $R_{\theta JC(top)}$          | Junction-to-case (top) thermal resistance    | 26.8       | °C/W |
| $R_{\theta JB}$               | Junction-to-board thermal resistance         | 43.5       | °C/W |
| $\Psi_{JT}$                   | Junction-to-top characterization parameter   | 4.8        | °C/W |
| $\Psi_{JB}$                   | Junction-to-board characterization parameter | 41.2       | °C/W |
| $R_{\theta JC(bot)}$          | Junction-to-case (bottom) thermal resistance | n/a        | °C/W |

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

## 6.5 Power Ratings

| PARAMETER |  | TEST CONDITIONS     | VALUE | UNIT |
|-----------|--|---------------------|-------|------|
| $P_D$     | Maximum power dissipation (both sides) | VDD1 = VDD2 = 5.5 V | 99    | mW   |
| $P_{D1}$  | Maximum power dissipation (high-side)  | VDD1 = 3.6 V        | 31    | mW   |
|           |  | VDD1 = 5.5 V        | 54    |      |
| $P_{D2}$  | Maximum power dissipation (low-side)   | VDD2 = 3.6 V        | 26    | mW   |
|           |  | VDD2 = 5.5 V        | 45    |      |

## 6.6 Insulation Specifications

over operating ambient temperature range (unless otherwise noted)

| PARAMETER   |   | TEST CONDITIONS  | VALUE              | UNIT             |
|---|---|--|--------------------|------------------|
| <b>GENERAL</b>  |   |  |                    |                  |
| CLR   | External clearance <sup>(1)</sup>                     | Shortest pin-to-pin distance through air   | ≥ 8.5              | mm               |
| CPG   | External creepage <sup>(1)</sup>                      | Shortest pin-to-pin distance across the package surface  | ≥ 8.5              | mm               |
| DTI   | Distance through insulation                           | Minimum internal gap (internal clearance) of the double insulation   | ≥ 0.021            | mm               |
| CTI   | Comparative tracking index                            | DIN EN 60112 (VDE 0303-11); IEC 60112  | ≥ 600              | V                |
|   | Material group  | According to IEC 60664-1   | I                  |                  |
|   | Overvoltage category per IEC 60664-1                  | Rated mains voltage ≤ 600 V <sub>RMS</sub>   | I-IV               |                  |
|   |   | Rated mains voltage ≤ 1000 V <sub>RMS</sub>  | I-III              |                  |
| <b>DIN VDE V 0884-11 (VDE V 0884-11): 2017-01<sup>(2)</sup></b> |   |  |                    |                  |
| V <sub>IORM</sub>   | Maximum repetitive peak isolation voltage             | AC voltage   | 1414               | V <sub>PK</sub>  |
| V <sub>IOWM</sub>   | Maximum-rated isolation working voltage               | AC voltage (sine wave)   | 1000               | V <sub>RMS</sub> |
|   |   | DC voltage   | 1414               | V <sub>DC</sub>  |
| V <sub>IOTM</sub>   | Maximum transient isolation voltage                   | V <sub>TEST</sub> = V <sub>IOTM</sub> , t = 60 s (qualification test)  | 4250               | V <sub>PK</sub>  |
|   |   | V <sub>TEST</sub> = 1.2 × V <sub>IOTM</sub> , t = 1 s (100% production test)   | 5100               |                  |
| V <sub>IOSM</sub>   | Maximum surge isolation voltage <sup>(3)</sup>        | Test method per IEC 60065, 1.2/50-μs waveform, V <sub>TEST</sub> = 1.6 × V <sub>IOSM</sub> = 7800 V <sub>PK</sub> (qualification)  | 6000               | V <sub>PK</sub>  |
| q <sub>pd</sub>   | Apparent charge <sup>(4)</sup>                        | Method b1, at preconditioning (type test), V <sub>ini</sub> = V <sub>IOTM</sub> , t <sub>ini</sub> = 1 s, V <sub>pd(m)</sub> = 1.5 × V <sub>IORM</sub> , t <sub>m</sub> = 1 s  | ≤ 5                | pC               |
|   |   | Method a, after input/output safety test subgroups 2 and 3, V <sub>ini</sub> = V <sub>IOTM</sub> , t <sub>ini</sub> = 60 s, V <sub>pd(m)</sub> = 1.2 × V <sub>IORM</sub> , t <sub>m</sub> = 10 s                     | ≤ 5                |                  |
|   |   | Method a, after environmental tests subgroup 1, V <sub>ini</sub> = V <sub>IOTM</sub> , t <sub>ini</sub> = 60 s, V <sub>pd(m)</sub> = 1.2 × V <sub>IORM</sub> , t <sub>m</sub> = 10 s                                 | ≤ 5                |                  |
|   |   | Method b3, at routine test (100% production), V <sub>ini</sub> = V <sub>IOTM</sub> = V <sub>pd(m)</sub> ; t <sub>ini</sub> = t <sub>m</sub> = 1 s  | ≤ 5                |                  |
| C <sub>IO</sub>   | Barrier capacitance, input to output <sup>(5)</sup>   | V <sub>IO</sub> = 0.5 V <sub>PP</sub> at 1 MHz   | ~1                 | pF               |
| R <sub>IO</sub>   | Insulation resistance, input to output <sup>(5)</sup> | V <sub>IO</sub> = 500 V at T <sub>A</sub> = 25°C   | > 10 <sup>12</sup> | Ω                |
|   |   | V <sub>IO</sub> = 500 V at 100°C ≤ T <sub>A</sub> ≤ 125°C  | > 10 <sup>11</sup> |                  |
|   |   | V <sub>IO</sub> = 500 V at T <sub>S</sub> = 150°C  | > 10 <sup>9</sup>  |                  |
|   | Pollution degree                                      |  | 2                  |                  |
|   | Climatic category                                     |  | 55/125/21          |                  |
| <b>UL1577</b>   |   |  |                    |                  |
| V <sub>ISO</sub>  | Withstand isolation voltage                           | V <sub>TEST</sub> = V <sub>ISO</sub> = 3000 V <sub>RMS</sub> or 4250 V <sub>DC</sub> , t = 60 s (qualification), V <sub>TEST</sub> = 1.2 × V <sub>ISO</sub> = 3600 V <sub>RMS</sub> , t = 1 s (100% production test) | 3000               | V <sub>RMS</sub> |

- (1) Apply creepage and clearance requirements according to the specific equipment isolation standards of an application. Care must be taken to maintain the creepage and clearance distance of a board design to ensure that the mounting pads of the isolator on the printed circuit board (PCB) do not reduce this distance. Creepage and clearance on a PCB become equal in certain cases. Techniques such as inserting grooves, ribs, or both on a PCB are used to help increase these specifications.
- (2) This coupler is suitable for *safe electrical insulation* only within the safety ratings. Compliance with the safety ratings shall be ensured by means of suitable protective circuits.
- (3) Testing is carried out in air or oil to determine the intrinsic surge immunity of the isolation barrier.
- (4) Apparent charge is electrical discharge caused by a partial discharge (pd).
- (5) All pins on each side of the barrier are tied together, creating a two-pin device.

## 6.7 Safety-Related Certifications

| VDE  | UL   |
|--|--|
| Certified according to DIN VDE V 0884-11 (VDE V 0884-11): 2017-01, DIN EN 60950-1 (VDE 0805 Teil 1): 2014-08, and DIN EN 60065 (VDE 0860): 2005-11 | Recognized under 1577 component recognition and CSA component acceptance NO 5 programs |
| Basic insulation   | Single protection  |
| Certificate number: Pending  | Certificate number: Pending  |

## 6.8 Safety Limiting Values

Safety limiting<sup>(1)</sup> intends to minimize potential damage to the isolation barrier upon failure of input or output circuitry. A failure of the I/O can allow low resistance to ground or the supply and, without current limiting, dissipate sufficient power to over-heat the die and damage the isolation barrier potentially leading to secondary system failures.

| PARAMETER |   | TEST CONDITIONS  | MIN | TYP | MAX  | UNIT             |
|-----------|---|--|-----|-----|------|------------------|
| $I_S$     | Safety input, output, or supply current | $R_{\theta JA} = 85.4^\circ\text{C/W}$ , $VDDx = 5.5\text{ V}$ ,<br>$T_J = 150^\circ\text{C}$ , $T_A = 25^\circ\text{C}$ |     |     | 266  | mA               |
| $I_S$     | Safety input, output, or supply current | $R_{\theta JA} = 85.4^\circ\text{C/W}$ , $VDDx = 3.6\text{ V}$ ,<br>$T_J = 150^\circ\text{C}$ , $T_A = 25^\circ\text{C}$ |     |     | 407  | mA               |
| $P_S$     | Safety input, output, or total power    | $R_{\theta JA} = 85.4^\circ\text{C/W}$ , $T_J = 150^\circ\text{C}$ , $T_A = 25^\circ\text{C}$                            |     |     | 1464 | mW               |
| $T_S$     | Maximum safety temperature              |  |     |     | 150  | $^\circ\text{C}$ |

- (1) The maximum safety temperature,  $T_S$ , has the same value as the maximum junction temperature,  $T_J$ , specified for the device. The  $I_S$  and  $P_S$  parameters represent the safety current and safety power, respectively. Do not exceed the maximum limits of  $I_S$  and  $P_S$ . These limits vary with the ambient temperature,  $T_A$ .

The junction-to-air thermal resistance,  $R_{\theta JA}$ , in the Thermal Information table is that of a device installed on a high-K test board for leaded surface-mount packages. Use these equations to calculate the value for each parameter:

$T_J = T_A + R_{\theta JA} \times P$ , where P is the power dissipated in the device.

$T_{J(\max)} = T_S = T_A + R_{\theta JA} \times P_S$ , where  $T_{J(\max)}$  is the maximum junction temperature.

$P_S = I_S \times VDD_{\max}$ , where  $VDD_{\max}$  is the maximum supply voltage for high-side and low-side.

## 6.9 Electrical Characteristics

minimum and maximum specifications apply from  $T_A = -55^\circ\text{C}$  to  $+125^\circ\text{C}$ ,  $V_{DD1} = 3.0\text{ V}$  to  $5.5\text{ V}$ ,  $V_{DD2} = 3.0\text{ V}$  to  $5.5\text{ V}$ ,  $I_{NP} = -50\text{ mV}$  to  $+50\text{ mV}$ , and  $I_{NN} = \text{GND1}$ ; typical specifications are at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = 5\text{ V}$ , and  $V_{DD2} = 3.3\text{ V}$  (unless otherwise noted)

| PARAMETER            | TEST CONDITIONS                                       | MIN  | TYP        | MAX       | UNIT                         |                             |
|----------------------|---|--|------------|-----------|------------------------------|-----------------------------|
| <b>ANALOG INPUT</b>  |   |  |            |           |                              |                             |
| $V_{CMov}$           | Common-mode overvoltage detection level               | $(V_{INP} + V_{INN}) / 2$ to GND1  |            | VDD1 – 2  |                              |                             |
|                      | Hysteresis of common-mode overvoltage detection level |  | 60         |           | mV                           |                             |
| $V_{OS}$             | Input offset voltage <sup>(1) (2)</sup>               | $T_A = 25^\circ\text{C}$ , $V_{INP} = V_{INN} = \text{GND1}$   |            | -50       | $\pm 2.5$ 50                 | $\mu\text{V}$               |
| $TCV_{OS}$           | Input offset drift <sup>(1) (2) (3)</sup>             |  | $\pm 0.15$ | 0.8       | $\mu\text{V}/^\circ\text{C}$ |                             |
| CMRR                 | Common-mode rejection ratio                           | $f_{IN} = 0\text{ Hz}$ , $V_{CM\ min} \leq V_{CM} \leq V_{CM\ max}$                                  |            | -100      |                              |                             |
|                      |   | $f_{IN} = 10\text{ kHz}$ , $V_{CM\ min} \leq V_{CM} \leq V_{CM\ max}$                                |            | -98       |                              |                             |
| $C_{IN}$             | Single-ended input capacitance                        | INN = GND1, $f_{IN} = 300\text{ kHz}$  |            | 4         |                              |                             |
| $C_{IND}$            | Differential input capacitance                        | $f_{IN} = 300\text{ kHz}$  |            | 2         |                              |                             |
| $R_{IN}$             | Single-ended input resistance                         | INN = GND1   |            | 4.75      |                              |                             |
| $R_{IND}$            | Differential input resistance                         |  |            | 4.9       |                              |                             |
| $I_{IB}$             | Input bias current                                    | INP = INN = GND1; $I_{IB} = (I_{IBP} + I_{IBN}) / 2$   |            | -48.5     | -36 -28.5                    | $\mu\text{A}$               |
| $TCI_{IB}$           | Input bias current drift                              |  |            | $\pm 1.5$ |                              | $\text{nA}/^\circ\text{C}$  |
| $I_{IO}$             | Input offset current                                  | $I_{IO} = I_{IBP} - I_{IBN}$   |            | $\pm 10$  |                              | nA                          |
| <b>ANALOG OUTPUT</b> |   |  |            |           |                              |                             |
|                      | Nominal gain  |  |            | 41        |                              |                             |
| $E_G$                | Gain error <sup>(1)</sup>                             | $T_A = 25^\circ\text{C}$   |            | -0.2%     | $\pm 0.04\%$ 0.2%            |                             |
| $TCE_G$              | Gain error drift <sup>(1) (4)</sup>                   |  |            | -35       | $\pm 3$ 35                   | $\text{ppm}/^\circ\text{C}$ |
|                      | Nonlinearity <sup>(1)</sup>                           |  |            | -0.03%    | $\pm 0.01\%$ 0.03%           |                             |
|                      | Nonlinearity drift                                    |  |            | 1         |                              | $\text{ppm}/^\circ\text{C}$ |
| THD                  | Total harmonic distortion                             | $f_{IN} = 10\text{ kHz}$   |            | -85       |                              | dB                          |
|                      | Output noise  | INP = INN = GND1, $f_{IN} = 0\text{ Hz}$ ,<br>BW = 100 kHz brickwall filter                          |            | 260       |                              | $\mu\text{V}_{RMS}$         |
| SNR                  | Signal-to-noise ratio                                 | $f_{IN} = 1\text{ kHz}$ , BW = 10 kHz  |            | 80        | 84                           |                             |
|                      |   | $f_{IN} = 10\text{ kHz}$ , BW = 100 kHz  |            | 70        |                              |                             |
| PSRR                 | Power-supply rejection ratio <sup>(2)</sup>           | PSRR vs VDD1, at DC  |            | -113      |                              |                             |
|                      |   | PSRR vs VDD1,<br>100-mV and 10-kHz ripple  |            | -108      |                              |                             |
|                      |   | PSRR vs VDD2, at DC  |            | -116      |                              |                             |
|                      |   | PSRR vs VDD2,<br>100-mV and 10-kHz ripple  |            | -87       |                              |                             |
| $V_{CMout}$          | Common-mode output voltage                            |  |            | 1.39      | 1.44 1.49                    | V                           |
| $V_{CLIPout}$        | Clipping differential output voltage                  | $V_{OUT} = (V_{OUTP} - V_{OUTN})$ ;<br>$ V_{IN}  =  V_{INP} - V_{INN}  >  V_{Clipping} $             |            | -2.52     | $\pm 2.49$ 2.52              | V                           |
| $V_{Failsafe}$       | Failsafe differential output voltage                  | $V_{CM} \geq V_{CMov}$ , or VDD1 missing   |            | -2.63     | -2.57 -2.53                  | V                           |
| BW                   | Output bandwidth                                      |  |            | 220       | 280                          | kHz                         |
| $R_{OUT}$            | Output resistance                                     | On OUTP or OUTN  |            | < 0.2     |                              | $\Omega$                    |
|                      | Output short-circuit current                          | On OUTP or OUTN, sourcing or sinking,<br>INN = INP = GND1, outputs shorted to<br>either GND2 or VDD2 |            | $\pm 14$  |                              | mA                          |
| CMTI                 | Common-mode transient immunity                        | $ GND1 - GND2  = 1\text{ kV}$  |            | 100       | 150                          | $\text{kV}/\mu\text{s}$     |



## 6.9 Electrical Characteristics (continued)

minimum and maximum specifications apply from  $T_A = -55^\circ\text{C}$  to  $+125^\circ\text{C}$ ,  $V_{DD1} = 3.0\text{ V}$  to  $5.5\text{ V}$ ,  $V_{DD2} = 3.0\text{ V}$  to  $5.5\text{ V}$ ,  $\text{INP} = -50\text{ mV}$  to  $+50\text{ mV}$ , and  $\text{INN} = \text{GND1}$ ; typical specifications are at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = 5\text{ V}$ , and  $V_{DD2} = 3.3\text{ V}$  (unless otherwise noted)

| PARAMETER           |                                       | TEST CONDITIONS                               | MIN | TYP | MAX | UNIT |
|---------------------|---------------------------------------|---|-----|-----|-----|------|
| <b>POWER SUPPLY</b> |                                       |   |     |     |     |      |
| $V_{DD1\text{POR}}$ | VDD1 power-on-reset threshold voltage | VDD1 falling                                  | 2.4 | 2.6 | 2.8 | V    |
| $I_{DD1}$           | High-side supply current              | $3.0\text{ V} \leq V_{DD1} \leq 3.6\text{ V}$ |     | 6.2 | 8.5 | mA   |
|                     |                                       | $4.5\text{ V} \leq V_{DD1} \leq 5.5\text{ V}$ |     | 7.2 | 9.8 |      |
| $I_{DD2}$           | Low-side supply current               | $3.0\text{ V} \leq V_{DD2} \leq 3.6\text{ V}$ |     | 5.3 | 7.2 |      |
|                     |                                       | $4.5\text{ V} \leq V_{DD2} \leq 5.5\text{ V}$ |     | 5.9 | 8.1 |      |

- The typical value includes one standard deviation ("sigma") at nominal operating conditions.
- This parameter is input referred.
- Offset error temperature drift is calculated using the box method, as described by the following equation:  

$$TCV_{OS} = (Value_{MAX} - Value_{MIN}) / TempRange$$
- Gain error temperature drift is calculated using the box method, as described by the following equation:  

$$TCE_G (\text{ppm}) = (Value_{MAX} - Value_{MIN}) / (Value_{(T=25^\circ\text{C})} \times TempRange) \times 10^6$$

## 6.10 Switching Characteristics

over operating free-air temperature range (unless otherwise noted)

| PARAMETER |  | TEST CONDITIONS   | MIN | TYP | MAX | UNIT          |
|-----------|--|---|-----|-----|-----|---------------|
| $t_r$     | Output signal rise time  |   |     | 1.5 |     | $\mu\text{s}$ |
| $t_f$     | Output signal fall time  |   |     | 1.5 |     | $\mu\text{s}$ |
|           | $V_{\text{INx}}$ to $V_{\text{OUTx}}$ signal delay (50% – 10%) | unfiltered output   |     | 1   | 1.5 | $\mu\text{s}$ |
|           | $V_{\text{INx}}$ to $V_{\text{OUTx}}$ signal delay (50% – 50%) | unfiltered output   |     | 1.6 | 2.1 | $\mu\text{s}$ |
|           | $V_{\text{INx}}$ to $V_{\text{OUTx}}$ signal delay (50% – 90%) | unfiltered output   |     | 2.5 | 3   | $\mu\text{s}$ |
| $t_{AS}$  | Analog settling time   | VDD1 step to 3.0 V with $V_{DD2} \geq 3.0\text{ V}$ , to $\text{OUTP}$ and $\text{OUTN}$ valid, 0.1% settling |     | 500 |     | $\mu\text{s}$ |

## 6.11 Timing Diagram

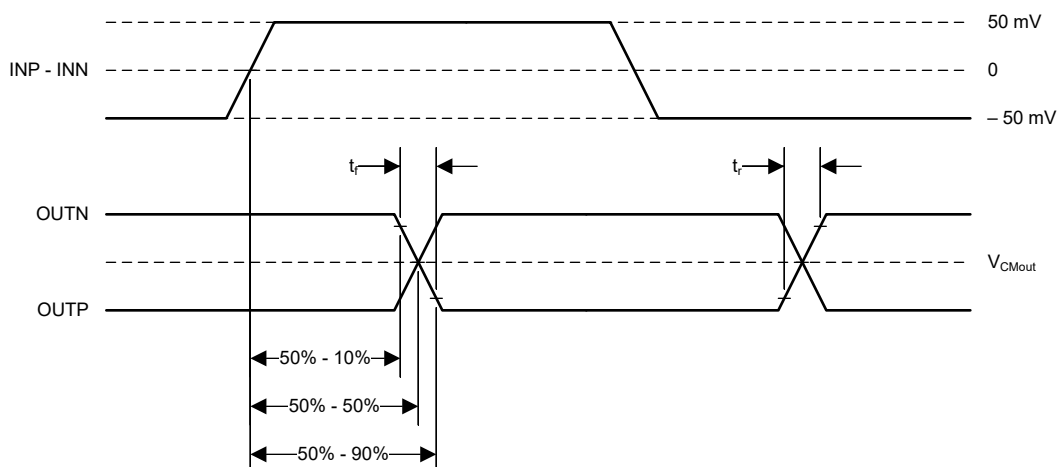
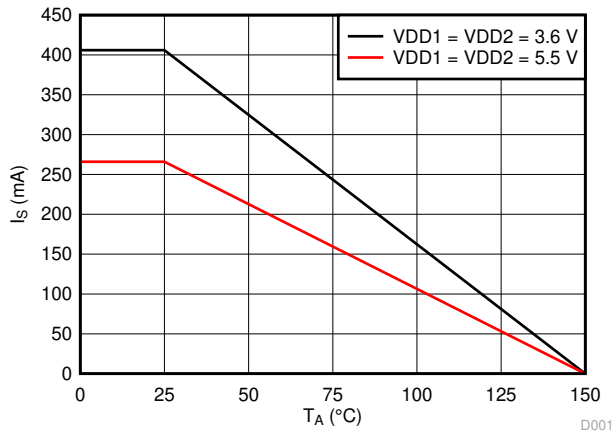
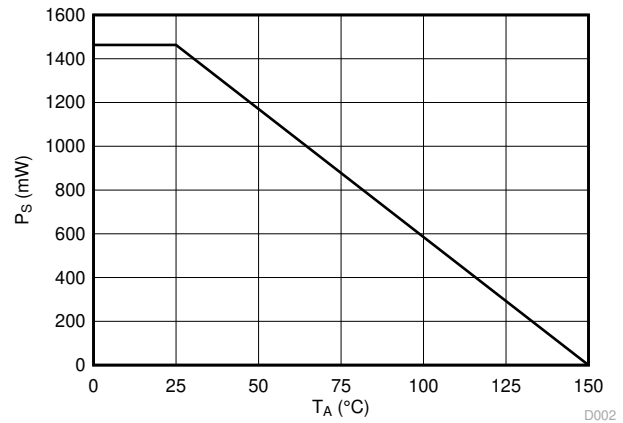


图 6-1. Rise, Fall, and Delay Time Waveforms

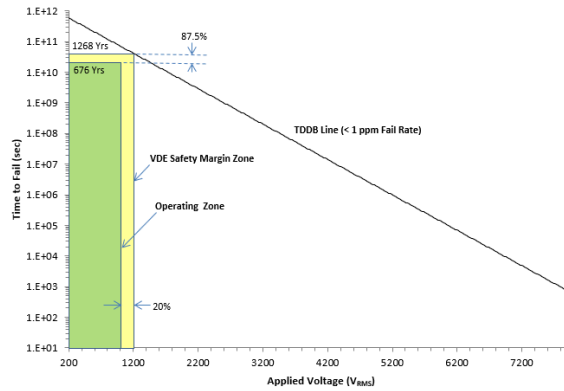
## 6.12 Insulation Characteristics Curves



**图 6-2. Thermal Derating Curve for Safety-Limiting Current per VDE**



**图 6-3. Thermal Derating Curve for Safety-Limiting Power per VDE**

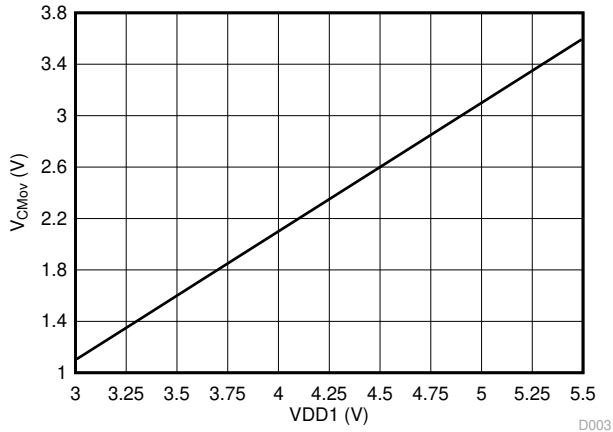


$T_A$  up to 150°C, stress-voltage frequency = 60 Hz, isolation working voltage = 1000  $V_{RMS}$ , operating lifetime = 676 years

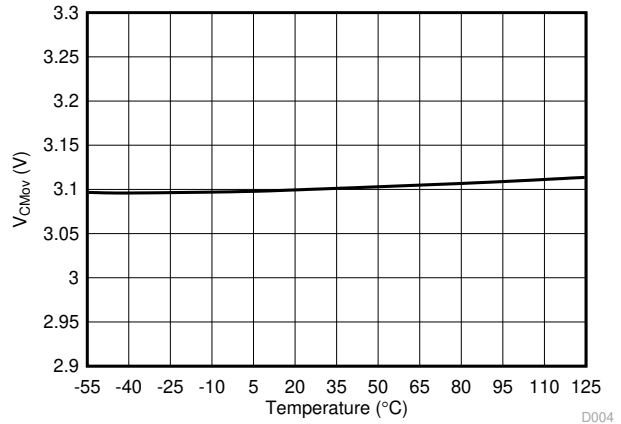
**图 6-4. Basic Isolation Capacitor Lifetime Projection**

### 6.13 Typical Characteristics

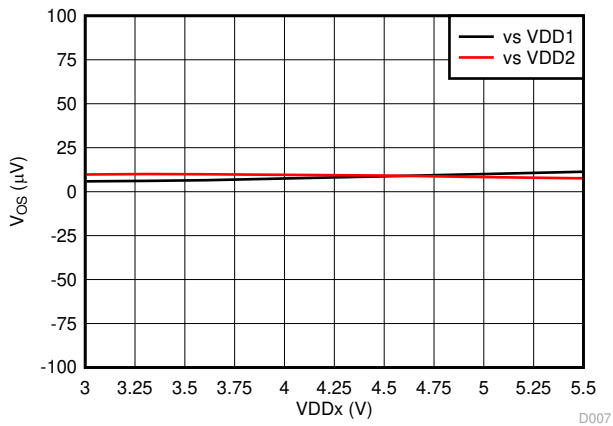
at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = 5\text{ V}$ ,  $V_{DD2} = 3.3\text{ V}$ ,  $\text{INP} = -50\text{ mV to } 50\text{ mV}$ ,  $\text{INN} = \text{GND1}$ , and  $f_{\text{IN}} = 10\text{ kHz}$  (unless otherwise noted)



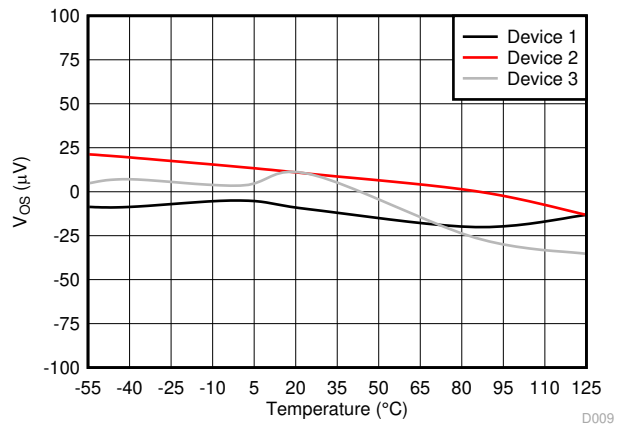
**图 6-5. Common-Mode Overtolerance Detection Level vs High-Side Supply Voltage**



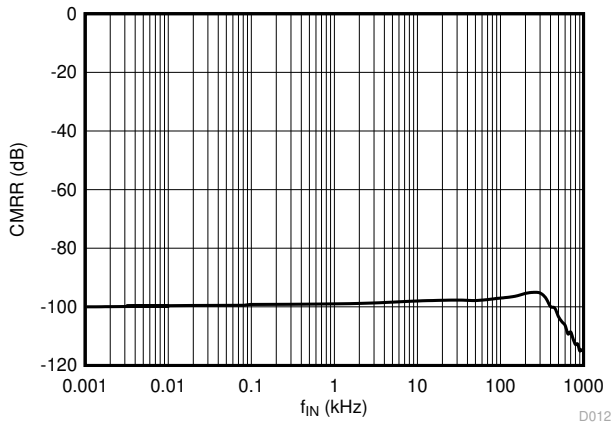
**图 6-6. Common-Mode Overtolerance Detection Level vs Temperature**



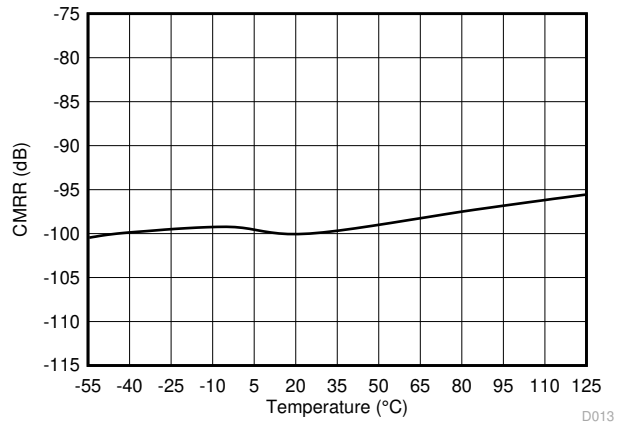
**图 6-7. Input Offset Voltage vs Supply Voltage**



**图 6-8. Input Offset Voltage vs Temperature**



**图 6-9. Common-Mode Rejection Ratio vs Input Frequency**



**图 6-10. Common-Mode Rejection Ratio vs Temperature**

### 6.13 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = 5\text{ V}$ ,  $V_{DD2} = 3.3\text{ V}$ ,  $\text{INP} = -50\text{ mV to } 50\text{ mV}$ ,  $\text{INN} = \text{GND1}$ , and  $f_{\text{IN}} = 10\text{ kHz}$  (unless otherwise noted)

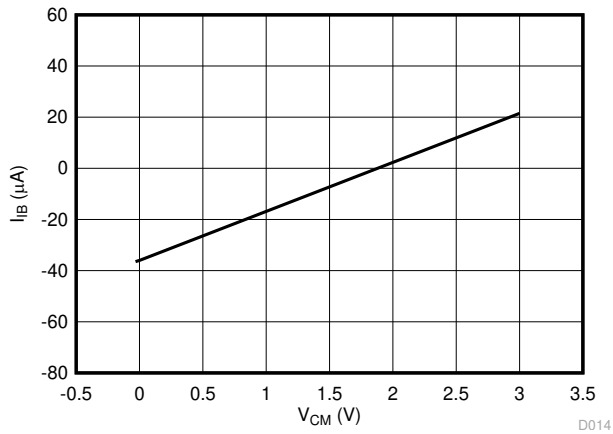


图 6-11. Input Bias Current vs Common-Mode Input Voltage

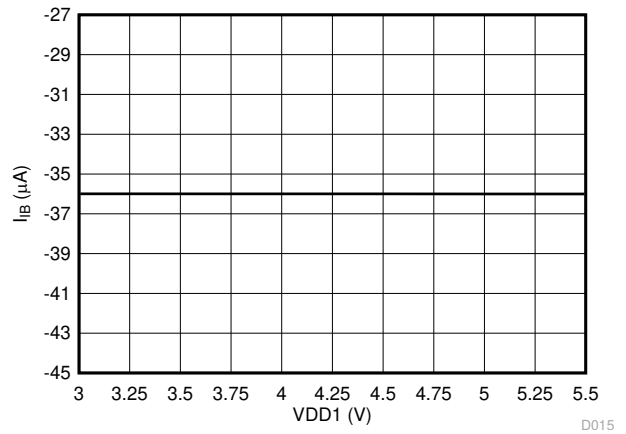


图 6-12. Input Bias Current vs High-Side Supply Voltage

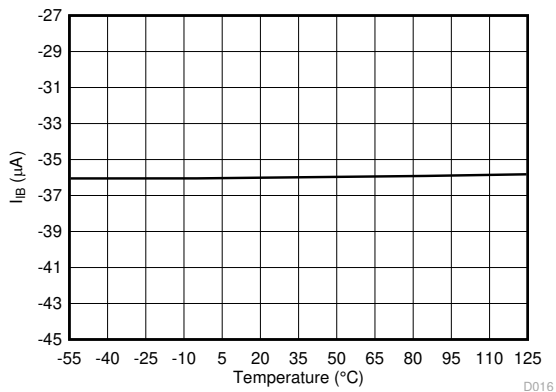


图 6-13. Input Bias Current vs Temperature

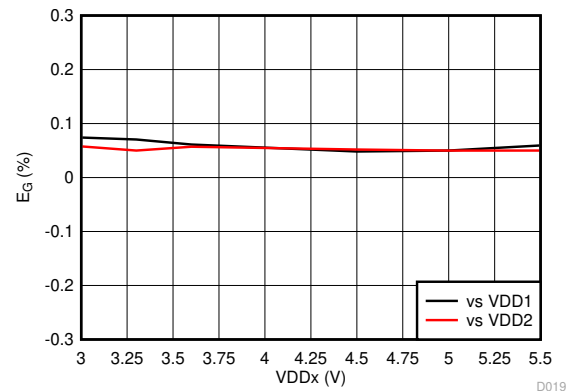


图 6-14. Gain Error vs Supply Voltage

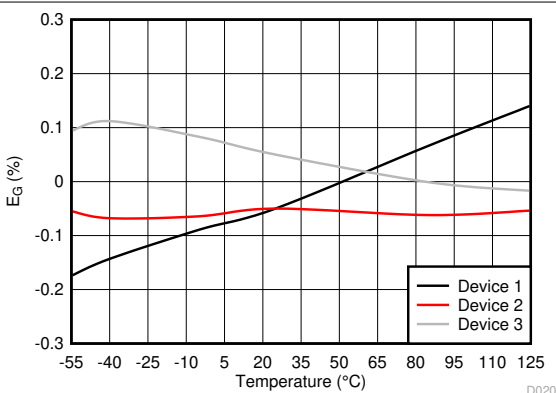


图 6-15. Gain Error vs Temperature

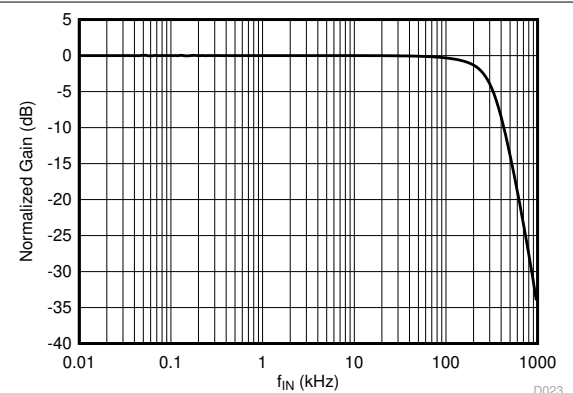


图 6-16. Normalized Gain vs Input Frequency

### 6.13 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = 5\text{ V}$ ,  $V_{DD2} = 3.3\text{ V}$ ,  $\text{INP} = -50\text{ mV to } 50\text{ mV}$ ,  $\text{INN} = \text{GND1}$ , and  $f_{\text{IN}} = 10\text{ kHz}$  (unless otherwise noted)

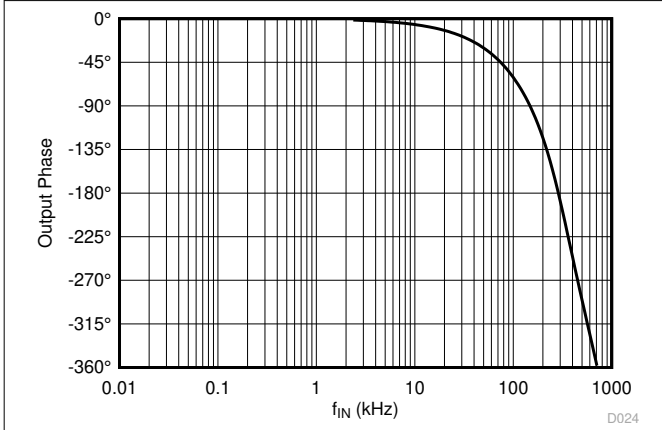


图 6-17. Output Phase vs Input Frequency

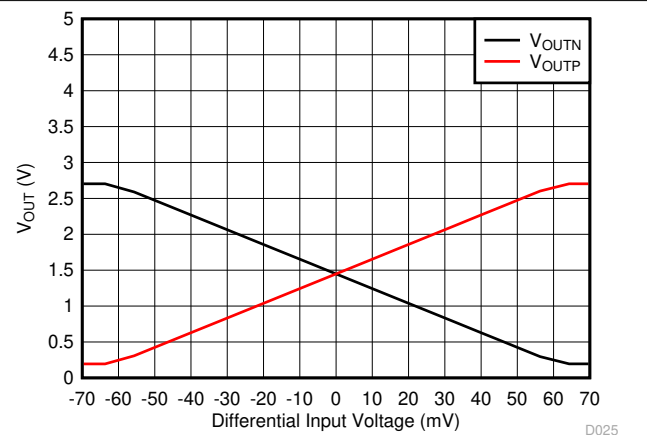


图 6-18. Output Voltage vs Input Voltage

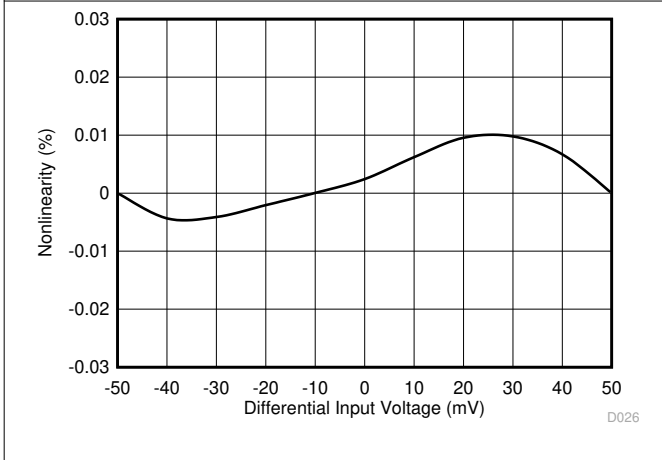


图 6-19. Nonlinearity vs Input Voltage

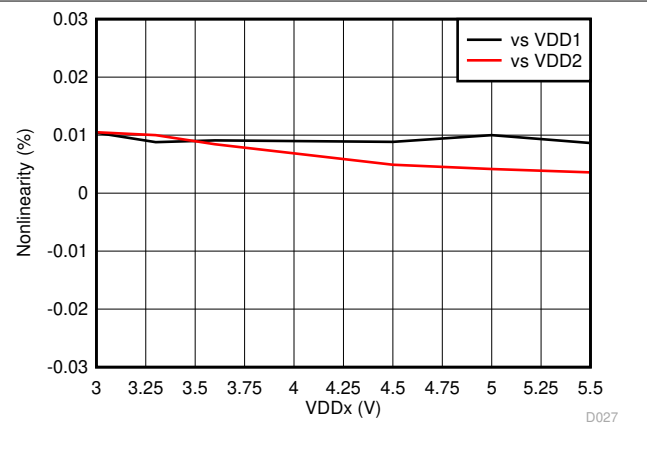


图 6-20. Nonlinearity vs Supply Voltage

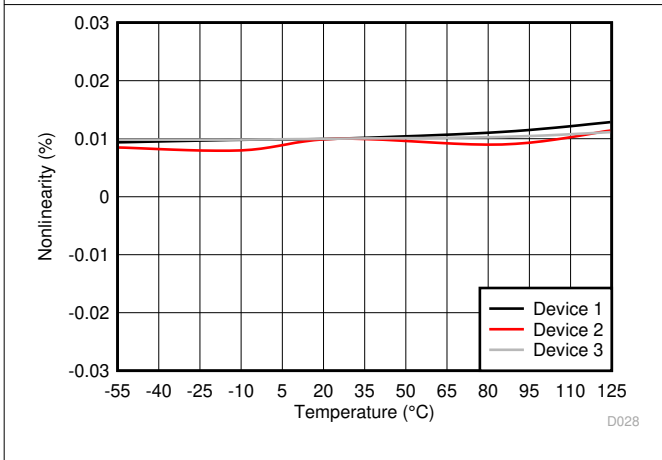


图 6-21. Nonlinearity vs Temperature

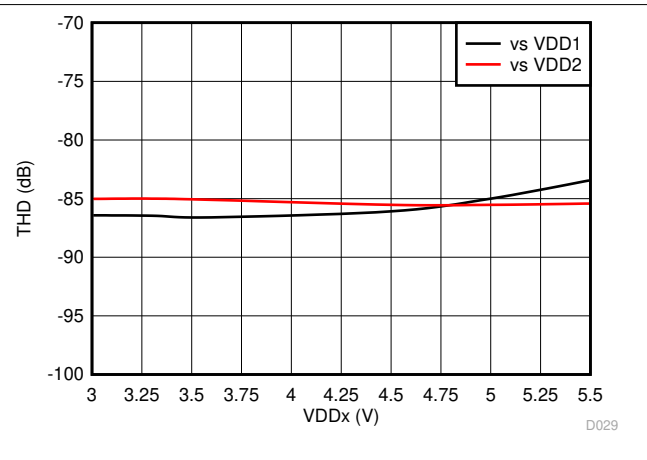


图 6-22. Total Harmonic Distortion vs Supply Voltage

### 6.13 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = 5\text{ V}$ ,  $V_{DD2} = 3.3\text{ V}$ ,  $\text{INP} = -50\text{ mV to } 50\text{ mV}$ ,  $\text{INN} = \text{GND1}$ , and  $f_{\text{IN}} = 10\text{ kHz}$  (unless otherwise noted)

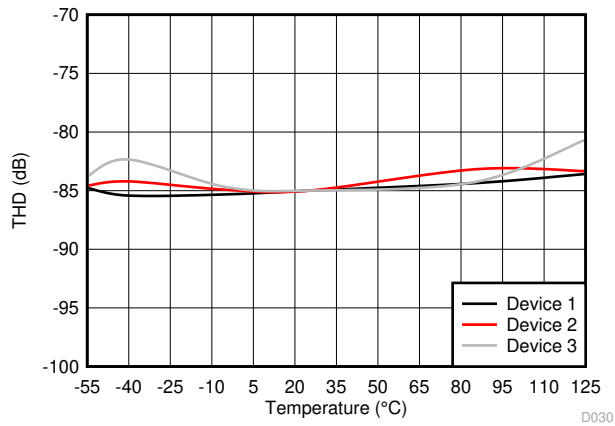


图 6-23. Total Harmonic Distortion vs Temperature

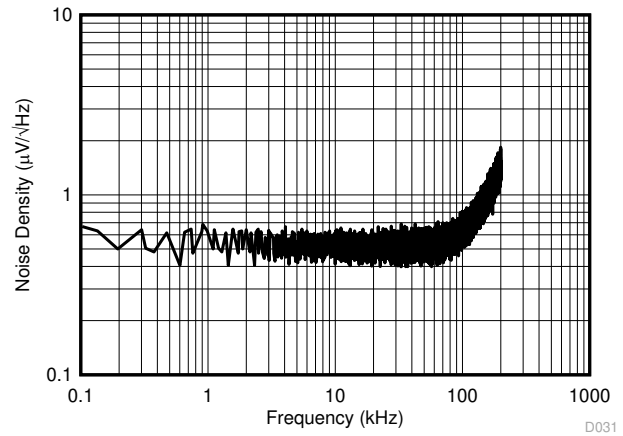


图 6-24. Output Noise Density vs Frequency

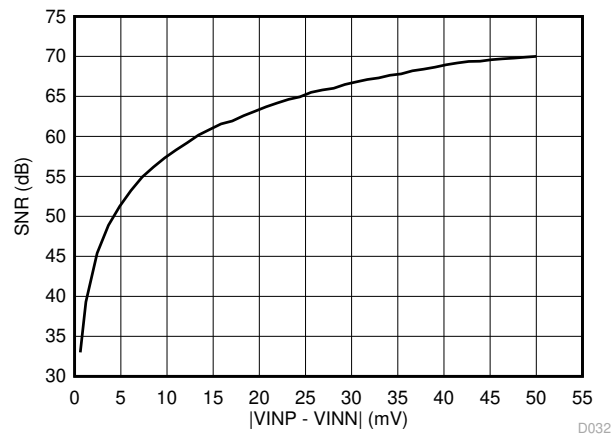


图 6-25. Signal-to-Noise Ratio vs Input Voltage

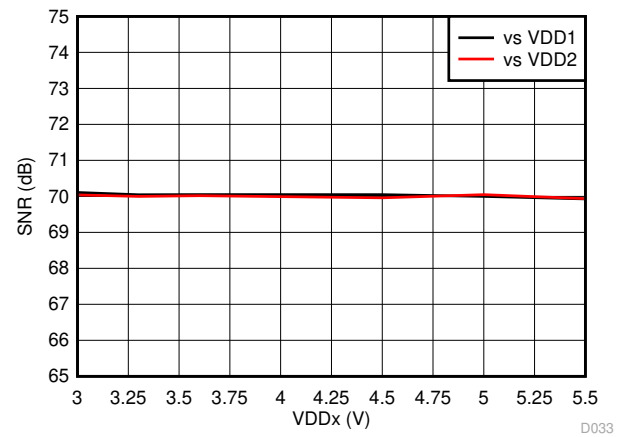


图 6-26. Signal-to-Noise Ratio vs Supply Voltage

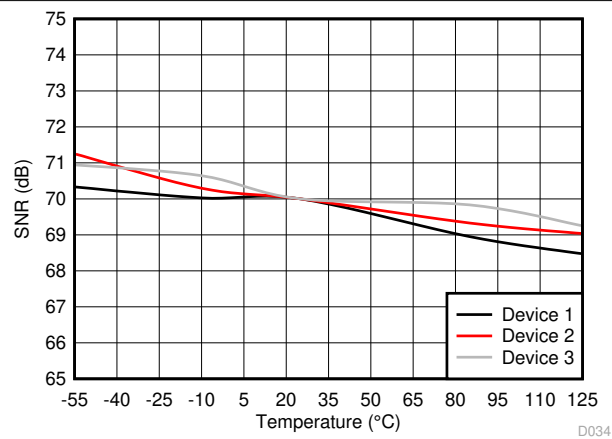


图 6-27. Signal-to-Noise Ratio vs Temperature

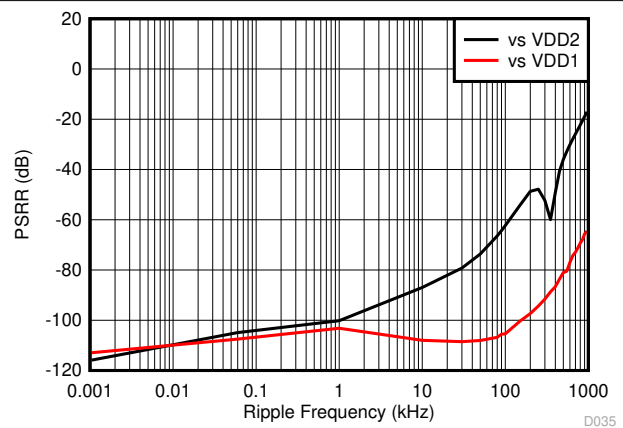
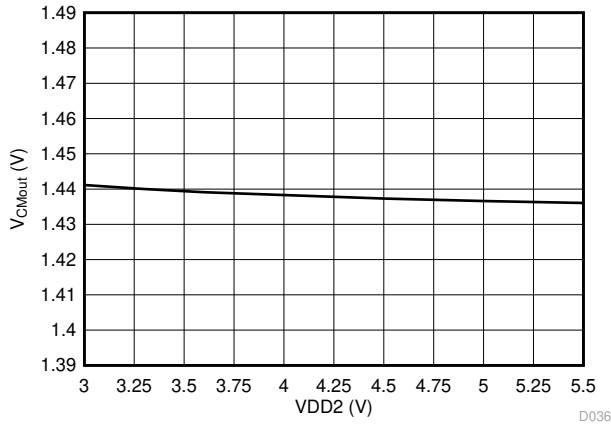


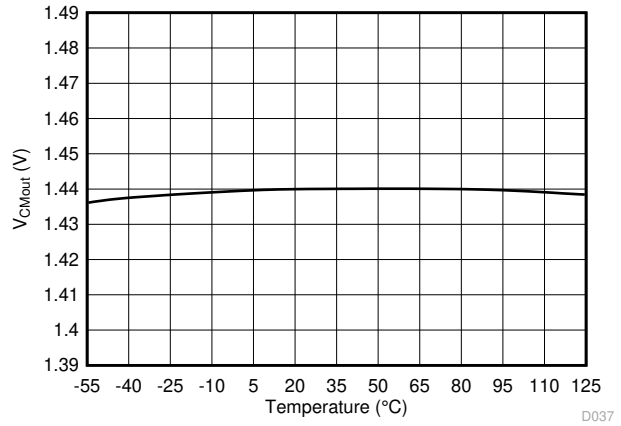
图 6-28. Power-Supply Rejection Ratio vs Ripple Frequency

### 6.13 Typical Characteristics (continued)

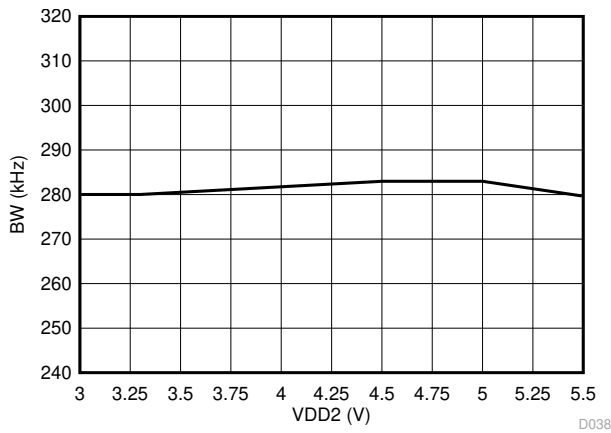
at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = 5\text{ V}$ ,  $V_{DD2} = 3.3\text{ V}$ ,  $\text{INP} = -50\text{ mV to } 50\text{ mV}$ ,  $\text{INN} = \text{GND1}$ , and  $f_{\text{IN}} = 10\text{ kHz}$  (unless otherwise noted)



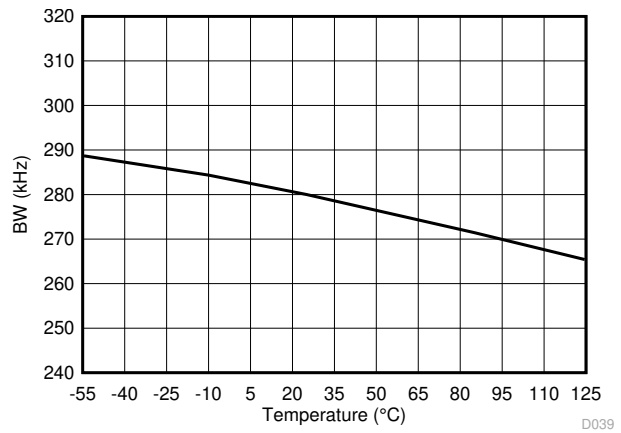
**图 6-29. Output Common-Mode Voltage vs Low-Side Supply Voltage**



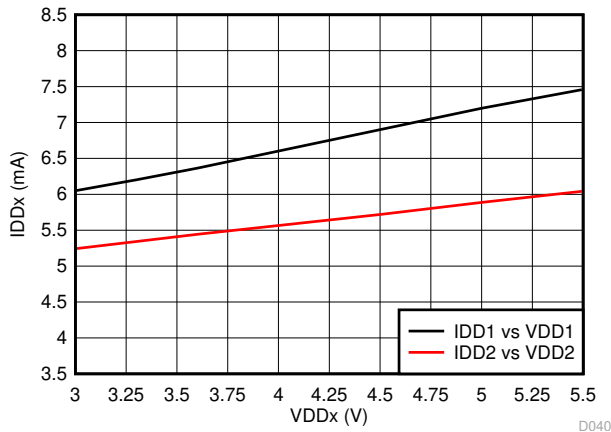
**图 6-30. Output Common-Mode Voltage vs Temperature**



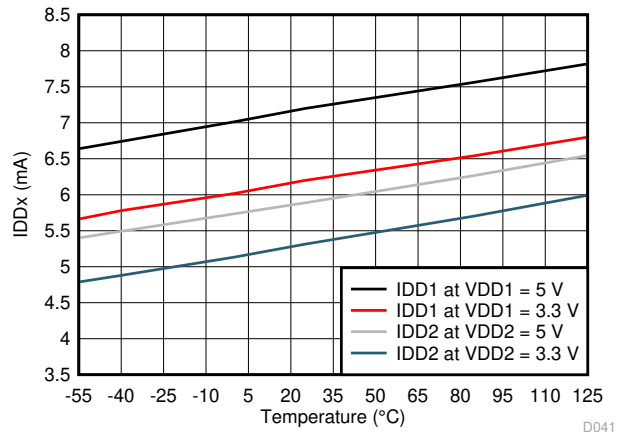
**图 6-31. Output Bandwidth vs Low-Side Supply Voltage**



**图 6-32. Output Bandwidth vs Temperature**



**图 6-33. Supply Current vs Supply Voltage**



**图 6-34. Supply Current vs Temperature**

### 6.13 Typical Characteristics (continued)

at  $T_A = 25^\circ\text{C}$ ,  $V_{DD1} = 5\text{ V}$ ,  $V_{DD2} = 3.3\text{ V}$ ,  $\text{INP} = -50\text{ mV to } 50\text{ mV}$ ,  $\text{INN} = \text{GND1}$ , and  $f_{\text{IN}} = 10\text{ kHz}$  (unless otherwise noted)

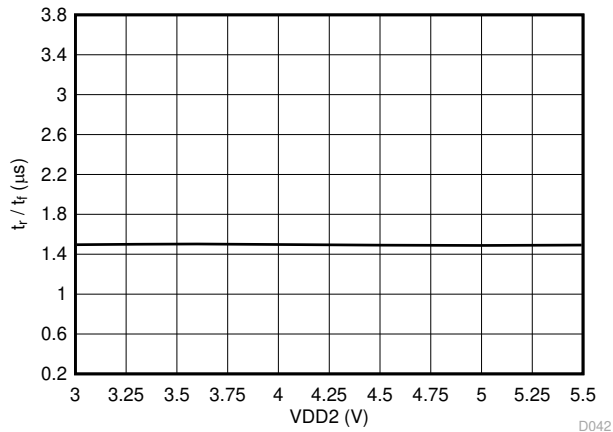


图 6-35. Output Rise and Fall Time vs Low-Side Supply Voltage

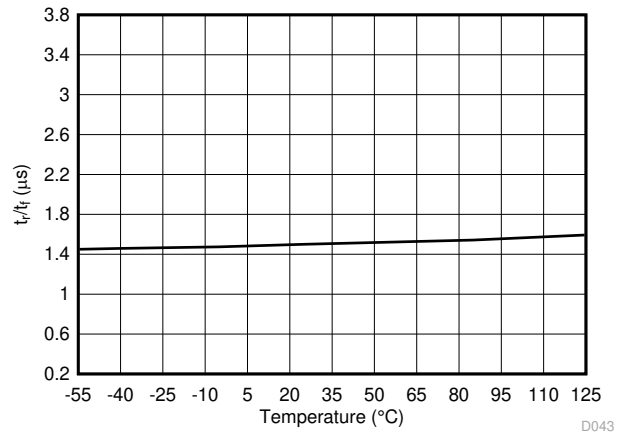


图 6-36. Output Rise and Fall Time vs Temperature

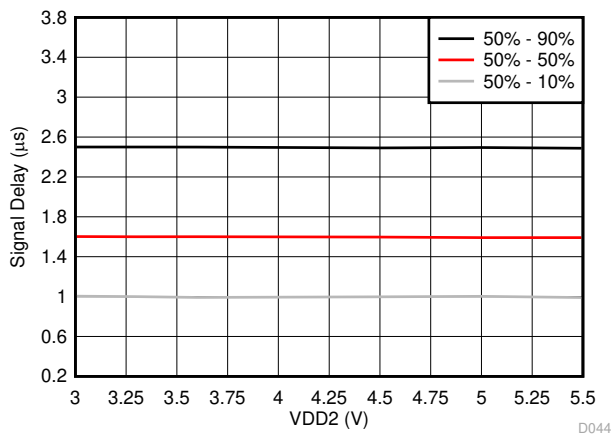


图 6-37.  $V_{\text{IN}}$  to  $V_{\text{OUT}}$  Signal Delay vs Low-Side Supply Voltage

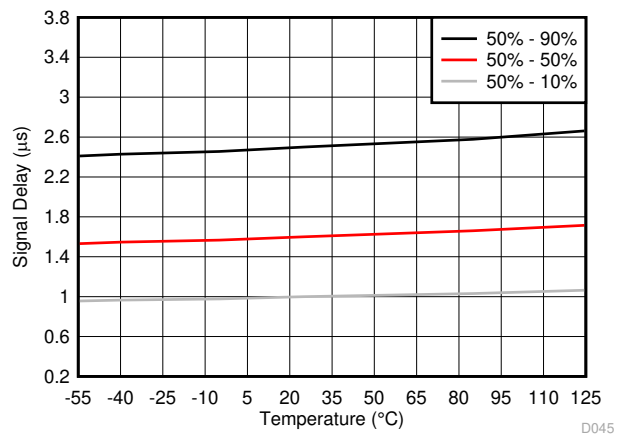


图 6-38.  $V_{\text{IN}}$  to  $V_{\text{OUT}}$  Signal Delay vs Temperature



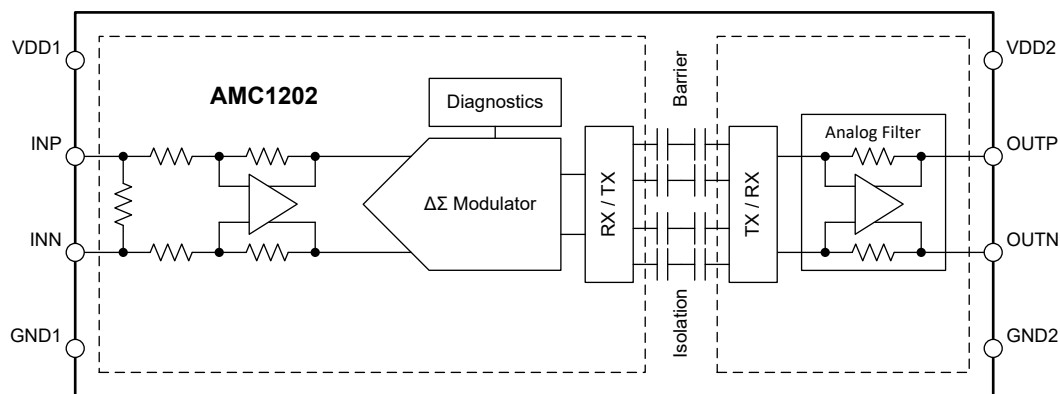
## 7 Detailed Description

### 7.1 Overview

The AMC1202 is a fully differential, precision, isolated amplifier. The input stage of the device consists of a fully differential amplifier that drives a second-order, delta-sigma ( $\Delta\Sigma$ ) modulator. The modulator converts the analog input signal into a digital bitstream that is transferred across the isolation barrier that separates the high-side from the low-side. On the low-side, the received bitstream is processed by a fourth-order analog filter that outputs a differential signal at the OUTP and OUTN pins that is proportional to the input signal.

The SiO<sub>2</sub>-based, capacitive isolation barrier supports a high level of magnetic field immunity, as described in the [ISO72x Digital Isolator Magnetic-Field Immunity application report](#). The digital modulation used in the AMC1202 to transmit data across the isolation barrier, and the isolation barrier characteristics itself, result in high reliability and common-mode transient immunity.

### 7.2 Functional Block Diagram



### 7.3 Feature Description

#### 7.3.1 Analog Input

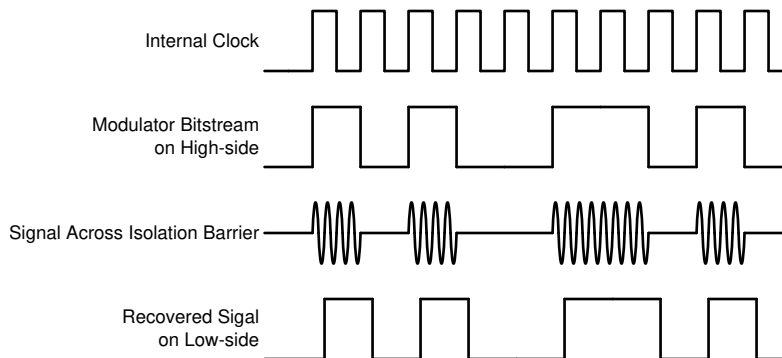
The differential amplifier input stage of the AMC1202 feeds a second-order, switched-capacitor, feed-forward  $\Delta\Sigma$  modulator. The gain of the differential amplifier is set by internal precision resistors with a differential input impedance of  $R_{IND}$ . The modulator converts the analog input signal into a bitstream that is transferred across the isolation barrier, as described in the [Isolation Channel Signal Transmission](#) section.

There are two restrictions on the analog input signals INP and INN. First, if the input voltages  $V_{INP}$  or  $V_{INN}$  exceed the range specified in the [Absolute Maximum Ratings](#) table, the input currents must be limited to the absolute maximum value, because the electrostatic discharge (ESD) protection turns on. In addition, the linearity and parametric performance of the device are ensured only when the analog input voltage remains within the linear full-scale range ( $V_{FSR}$ ) and within the common-mode input voltage range ( $V_{CM}$ ) as specified in the [Recommended Operating Conditions](#) table.

### 7.3.2 Isolation Channel Signal Transmission

The AMC1202 uses an on-off keying (OOK) modulation scheme, as shown in [Figure 7-1](#), to transmit the modulator output bitstream across the SiO<sub>2</sub>-based isolation barrier. The transmit driver (TX) shown in the [Functional Block Diagram](#) transmits an internally-generated, high-frequency carrier across the isolation barrier to represent a digital *one* and does not send a signal to represent a digital *zero*. The nominal frequency of the carrier used inside the AMC1202 is 480 MHz.

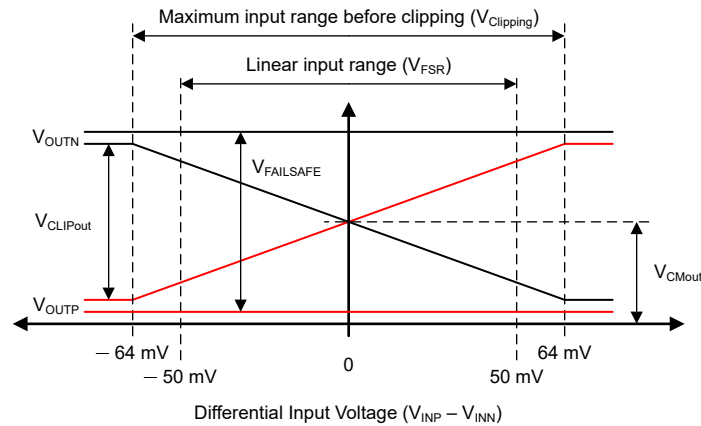
The receiver (RX) on the other side of the isolation barrier recovers and demodulates the signal and provides the input to the 4th-order analog filter. The AMC1202 transmission channel is optimized to achieve the highest level of common-mode transient immunity (CMTI) and lowest level of radiated emissions caused by the high-frequency carrier and RX/TX buffer switching.



**图 7-1. OOK-Based Modulation Scheme**

### 7.3.3 Analog Output

The AMC1202 offers a differential analog output comprised of the OOUTP and OOUTN pins. For differential input voltages ( $V_{INP} - V_{INN}$ ) in the range from  $-50\text{ mV}$  to  $50\text{ mV}$ , the device provides a linear response with a nominal gain of 41. For example, for a differential input voltage of  $50\text{ mV}$ , the differential output voltage ( $V_{OOUTP} - V_{OOUTN}$ ) is  $2.05\text{ V}$ . At zero input (INP shorted to INN), both pins output the same common-mode output voltage  $V_{CMout}$ , as specified in the [Electrical Characteristics](#) table. For absolute differential input voltages greater than  $50\text{ mV}$  but less than  $64\text{ mV}$ , the differential output voltage continues to increase in magnitude but with reduced linearity performance. The outputs saturate at a differential output voltage of  $V_{CLIPout}$ , as shown in [Figure 7-2](#), if the differential input voltage exceeds the  $V_{Clipping}$  value.



**图 7-2. Output Behavior of the AMC1202**

The AMC1202 offers a fail-safe feature that simplifies diagnostics on system level. [Figure 7-2](#) shows the fail-safe mode, in which the AMC1202 outputs a negative differential output voltage that does not occur under normal operating conditions. The fail-safe output is active in two cases:

- When the high-side supply is missing or below the  $V_{DD1UV}$  threshold
- When the common-mode input voltage, that is  $V_{CM} = (V_{INP} + V_{INN}) / 2$ , exceeds the common-mode overvoltage detection level  $V_{CMov}$

Use the maximum  $V_{FAILSAFE}$  voltage specified in the [Electrical Characteristics](#) table as a reference value for fail-safe detection on system level.

### 7.4 Device Functional Modes

The AMC1202 is operational when the power supplies  $V_{DD1}$  and  $V_{DD2}$  are applied, as specified in the [Recommended Operating Conditions](#) table.

## 8 Application and Implementation

### Note

以下应用部分中的信息不属于 TI 器件规格的范围，TI 不担保其准确性和完整性。TI 的客户应负责确定器件是否适用于其应用。客户应验证并测试其设计，以确保系统功能。

### 8.1 Application Information

The low analog input voltage range, excellent accuracy, and low temperature drift make the a high-performance solution for industrial applications where shunt-based current sensing in the presence of high common-mode voltage levels is required.

### 8.2 Typical Application

The AMC1202 is ideally suited for shunt-based current sensing applications where accurate current monitoring is required in the presence of high common-mode voltages.

图 8-1 shows the AMC1202 in a typical application. The load current flowing through an external shunt resistor RSHUNT produces a voltage drop that is sensed by the AMC1202. The AMC1202 digitizes the analog input signal on the high-side, transfers the data across the isolation barrier to the low-side, reconstructs the analog signal, and presents that signal as a differential voltage on the output pins.

The differential input, differential output, and the high common-mode transient immunity (CMTI) of the AMC1202 ensure reliable and accurate operation even in high-noise environments.

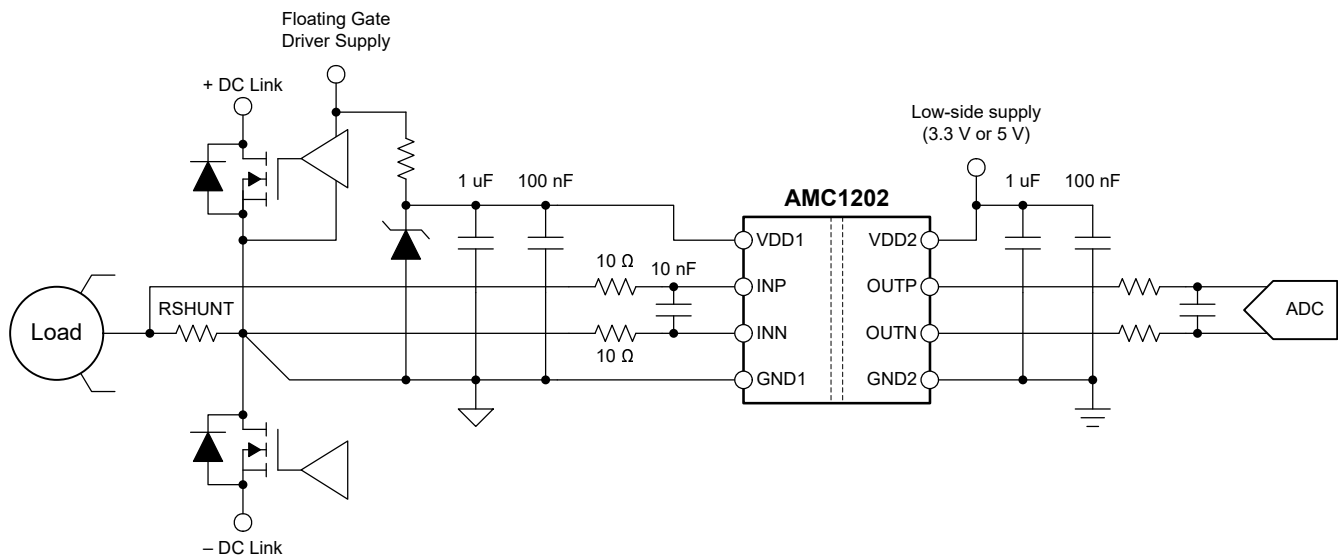


图 8-1. Using the AMC1202 for Current Sensing in a Typical Application

## 8.2.1 Design Requirements

表 8-1 lists the parameters for this typical application.

表 8-1. Design Requirements

| PARAMETER  | VALUE            |
|--|------------------|
| High-side supply voltage                             | 3.3 V or 5 V     |
| Low-side supply voltage                              | 3.3 V or 5 V     |
| Voltage drop across RSHUNT for a linear response     | ±50 mV (maximum) |
| Signal delay (50% V <sub>IN</sub> to 90% OUTP, OUTN) | 3 μs (maximum)   |

## 8.2.2 Detailed Design Procedure

In 图 8-1, the high-side power supply (VDD1) for the AMC1202 is derived from the floating power supply of the upper gate driver.

The floating ground reference (GND1) is derived from the end of the shunt resistor that is connected to the negative input of the AMC1202 (INN). If a four-pin shunt is used, the inputs of the AMC1202 are connected to the inner leads and GND1 is connected to the outer lead on the INN-side of the shunt. To minimize offset and improve accuracy, route the ground connection as a separate trace that connects directly to the shunt resistor rather than shorting GND1 to INN directly at the input to the device. See the [Layout](#) section for more details.

### 8.2.2.1 Shunt Resistor Sizing

Use Ohm's Law to calculate the voltage drop across the shunt resistor ( $V_{SHUNT}$ ) for the desired measured current:  $V_{SHUNT} = I \times R_{SHUNT}$ .

Consider the following two restrictions when selecting the value of the shunt resistor, RSHUNT:

- The voltage drop caused by the nominal current range must not exceed the recommended differential input voltage range for a linear response:  $|V_{SHUNT}| \leq |V_{FSR}|$
- The voltage drop caused by the maximum allowed overcurrent must not exceed the input voltage that causes a clipping output:  $|V_{SHUNT}| \leq |V_{Clipping}|$

### 8.2.2.2 Input Filter Design

TI recommends placing an RC-filter in front of the isolated amplifier to improve signal-to-noise performance of the signal path. Design the input filter such that:

- The cutoff frequency of the filter is at least one order of magnitude lower than the sampling frequency (20 MHz) of the  $\Delta\Sigma$  modulator
- The input bias current does not generate significant voltage drop across the DC impedance of the input filter
- The impedances measured from the analog inputs are equal

For most applications, the structure shown in 图 8-2 achieves excellent performance.

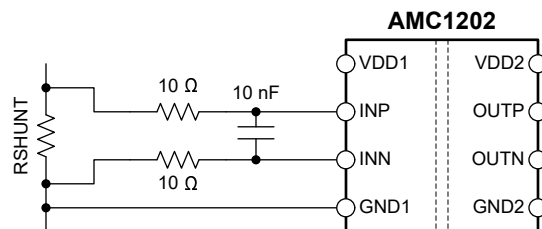


图 8-2. Differential Input Filter

### 8.2.2.3 Differential to Single-Ended Output Conversion

图 8-3 shows an example of a TLV6001-based signal conversion and filter circuit for systems using single-ended-input ADCs to convert the analog output voltage into digital. With  $R1 = R2 = R3 = R4$ , the output voltage equals  $(V_{OUTP} - V_{OUTN}) + V_{REF}$ . Tailor the bandwidth of this filter stage to the bandwidth requirement of the system. For most applications,  $R1 = R2 = R3 = R4 = 3.3\text{ k}\Omega$  and  $C1 = C2 = 330\text{ pF}$  yields good performance.

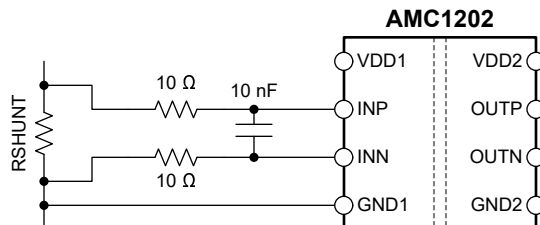


图 8-3. Connecting the AMC1202 Output to a Single-Ended Input ADC

For more information on the general procedure to design the filtering and driving stages of SAR ADCs, see the [18-Bit, 1MSPS Data Acquisition Block \(DAQ\) Optimized for Lowest Distortion and Noise](#) and [18-Bit Data Acquisition Block \(DAQ\) Optimized for Lowest Power](#) reference guides, available for download at [www.ti.com](http://www.ti.com).

### 8.2.3 Application Curve

One important aspect of power-stage design is the effective detection of an overcurrent condition to protect the switching devices and passive components from damage. To power off the system quickly in the event of an overcurrent condition, a low delay caused by the isolated amplifier is required. 图 8-4 shows the typical full-scale step response of the AMC1202.



图 8-4. Step Response of the AMC1202

### 8.2.4 What to Do and What Not to Do

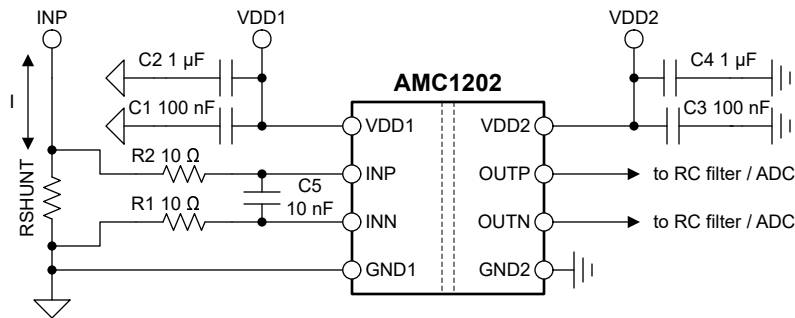
Do not leave the inputs of the AMC1202 unconnected (floating) when the device is powered up. If the device inputs are left floating, the input bias current may drive the inputs to a positive value that exceeds the operating common-mode input voltage and the device outputs the fail-safe voltage as described in the [Analog Output](#) section.

Connect the high-side ground (GND1) to INN, either by a hard short or through a resistive path. A DC current path between INN and GND1 is required to define the input common-mode voltage. Do not exceed the input common-mode range as specified in the [Recommended Operating Conditions](#) table. For best accuracy, route the ground connection as a separate trace that connects directly to the shunt resistor rather than shorting GND1 to INN directly at the input to the device. See the [Layout](#) section for more details.

## 9 Power Supply Recommendations

The AMC1202 does not require any specific power up sequencing. The high-side power-supply (VDD1) is decoupled with a low-ESR 100-nF capacitor (C1) parallel to a low-ESR 1- $\mu$ F capacitor (C2). The low-side power supply (VDD2) is equally decoupled with a low-ESR 100-nF capacitor (C3) parallel to a low-ESR 1- $\mu$ F capacitor (C4). Place all four capacitors (C1, C2, C3, and C4) as close to the device as possible.

The ground reference for the high-side (GND1) is derived from the end of the shunt resistor, which is connected to the negative input (INN) of the device. For best DC accuracy, use a separate trace (as shown in [图 9-1](#)) to make this connection instead of shorting GND1 to INN directly at the device input. If a four-terminal shunt is used, the device inputs are connected to the inner leads and GND1 is connected to the outer lead on the INN-side of the shunt.



**图 9-1. Decoupling of the AMC1202**

Capacitors must provide adequate effective capacitance under the applicable DC bias conditions they experience in the application. Multilayer ceramic capacitors (MLCCs) typically exhibit only a fraction of their nominal capacitance under real-world conditions and this factor must be taken into consideration when selecting these capacitors. This problem is especially acute in low-profile capacitors, in which the dielectric field strength is higher than in taller components. Reputable capacitor manufacturers provide capacitance versus DC bias curves that greatly simplify component selection.

## 10 Layout

### 10.1 Layout Guidelines

Figure 10-1 shows a layout recommendation with the critical placement of the decoupling capacitors (as close as possible to the AMC1202 supply pins) and placement of the other components required by the device. For best performance, place the shunt resistor close to the INP and INN inputs of the AMC1202 and keep the layout of both connections symmetrical.

### 10.2 Layout Example

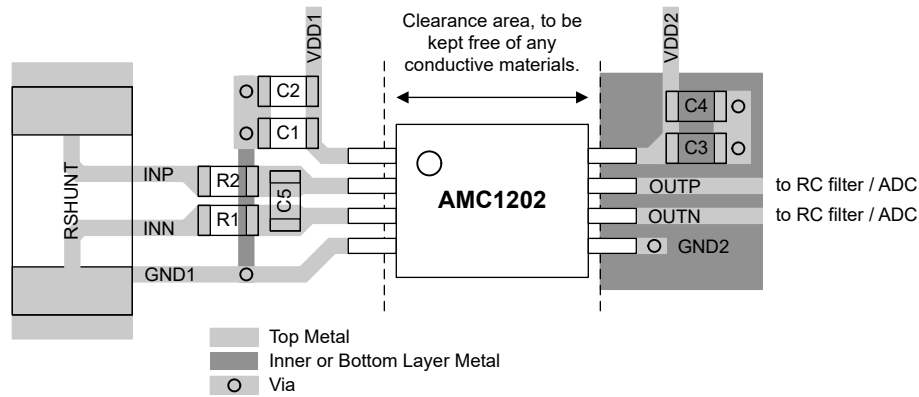


Figure 10-1. Recommended Layout of the AMC1202



## 11 Device and Documentation Support

### 11.1 Documentation Support

#### 11.1.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, [Isolation Glossary application report](#)
- Texas Instruments, [Semiconductor and IC Package Thermal Metrics application report](#)
- Texas Instruments, [ISO72x Digital Isolator Magnetic-Field Immunity application report](#)
- Texas Instruments, [TLV600x Low-Power, Rail-to-Rail In/Out, 1-MHz Operational Amplifier for Cost-Sensitive Systems data sheet](#)
- Texas Instruments, [18-Bit, 1-MSPS Data Acquisition Block \(DAQ\) Optimized for Lowest Distortion and Noise reference guide](#)
- Texas Instruments, [18-Bit, 1-MSPS Data Acquisition Block \(DAQ\) Optimized for Lowest Power reference guide](#)
- Texas Instruments, [Isolated Amplifier Voltage Sensing Excel Calculator design tool](#)

### 11.2 Trademarks

所有商标均为其各自所有者的财产。

### 11.3 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 11.4 术语表

#### TI 术语表

本术语表列出并解释了术语、首字母缩略词和定义。

## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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**PACKAGING INFORMATION**

| Orderable Device | Status<br>(1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan<br>(2) | Lead finish/<br>Ball material<br>(6) | MSL Peak Temp<br>(3) | Op Temp (°C) | Device Marking<br>(4/5) | Samples |
|------------------|---------------|--------------|-----------------|------|-------------|-----------------|--------------------------------------|----------------------|--------------|-------------------------|---------|
| AMC1202DWVR      | ACTIVE        | SOIC         | DWV             | 8    | 1000        | RoHS & Green    | NIPDAU                               | Level-3-260C-168 HR  | -40 to 125   | AMC1202                 | Samples |

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

| Device      | Package Type | Package Drawing | Pins | SPQ  | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|-------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| AMC1202DWVR | SOIC         | DWV             | 8    | 1000 | 330.0              | 16.4               | 12.05   | 6.15    | 3.3     | 16.0    | 16.0   | Q1            |

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

| Device      | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|-------------|--------------|-----------------|------|------|-------------|------------|-------------|
| AMC1202DWVR | SOIC         | DWV             | 8    | 1000 | 350.0       | 350.0      | 43.0        |

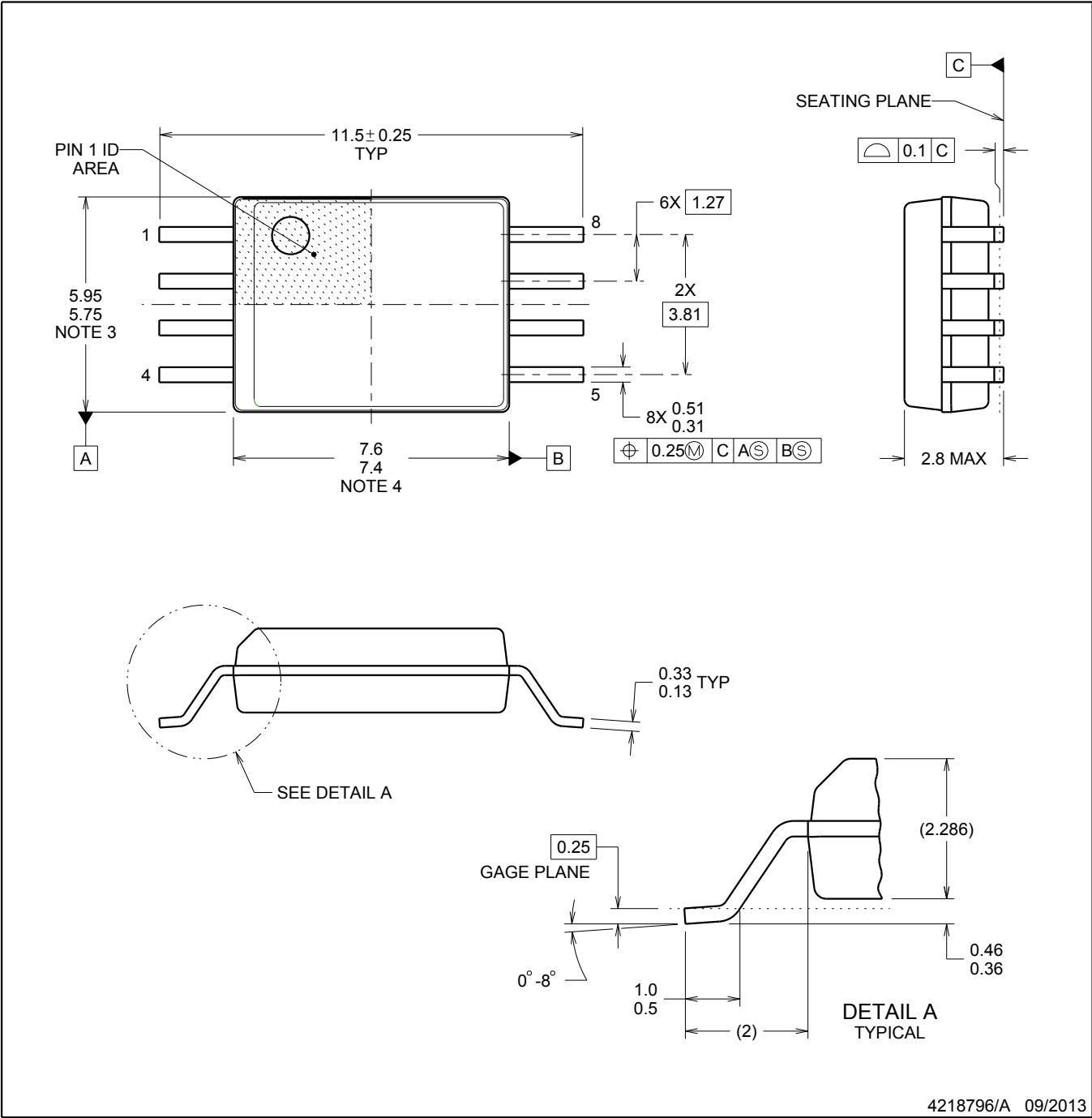
# PACKAGE OUTLINE

DWV0008A



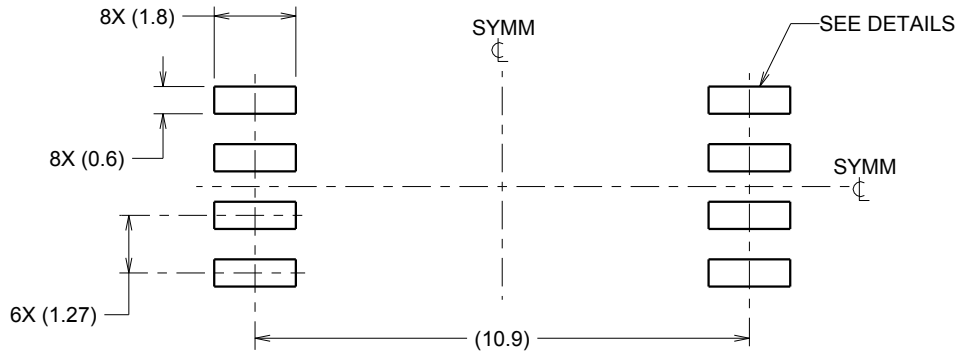
SOIC - 2.8 mm max height

SOIC

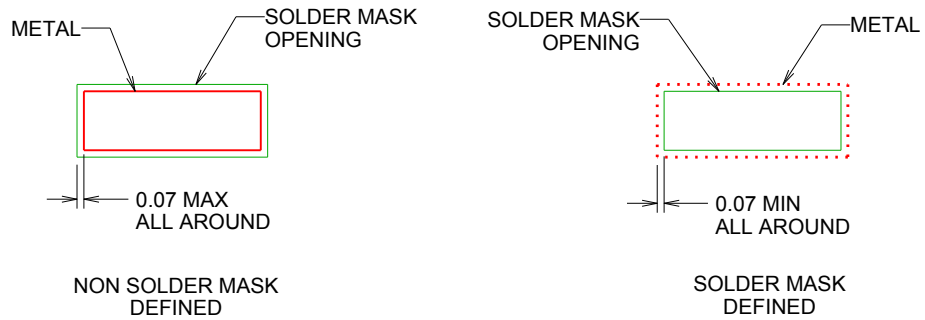


**NOTES:**

1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm, per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm, per side.



LAND PATTERN EXAMPLE  
 9.1 mm NOMINAL CLEARANCE/CREEPAGE  
 SCALE:6X

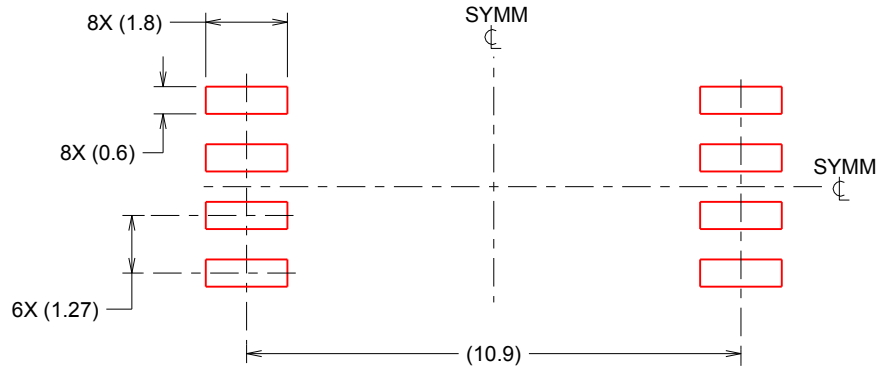


SOLDER MASK DETAILS

4218796/A 09/2013

NOTES: (continued)

- 5. Publication IPC-7351 may have alternate designs.
- 6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SOLDER PASTE EXAMPLE  
 BASED ON 0.125 mm THICK STENCIL  
 SCALE:6X

4218796/A 09/2013

NOTES: (continued)

- 7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 8. Board assembly site may have different recommendations for stencil design.



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